Technical specification for LIDAR (Light Detection and Ranging)

Sr	Specification					
No						
No						
3.	Tashnical Specifications					
J.	Technical Specifications: Class I Laser not requiring protective eyewear during operation					
	Wavelength of the laser must be absorbable by water					
	Measuring at least 300,000 points/second					
	• At least 100 m range					
	At least 16 channels					
	Range accuracy less that 4 cm					
	• Field of view (horizontal x vertical) 360° x 20°-30° or more					
	• Angular Resolution (Horizontal/Azimuth): $0.1^{\circ} - 0.4^{\circ}$					
	• Vertical angular resolution less than 2°					
	ROS (Robot Operating System) support must be included					
	Warranty:					
	Standard warranty for 1 year and extended warranty as optional for 2 additional					
	years Operating Manual:					
	Both electronic and hard copy					
	 The documentation/manual shall include all drawings, schematics, 					
	spare parts, catalogues and sub-vendor's manuals					
	Installation:					
	• The system shall be installed/commissioned at the customer site. The					
	quotation shall be inclusive of all charges, if any, for installation and					
	commissioning of the equipment by the vendor.					
	 Extensive operation, integration and maintenance training for two 					
	persons for one week at the customer site during and after the					
	installation should be included.					
	• Vendor needs to confirm the suitability of the system offered to be able					
	to upgrade this facilities on-site Eligibility Criteria:					
	 Vendor shall provide a list of at least 2 customers (India and abroad) of 					
	similar systems along with email addresses, where similar systems					
	have already been installed as a part of the technical bid.					
	An authorized service center in India should be available, functioning					
	for minimum of 2 years to provide repair, maintenance, calibration and					
	upgradation facility.					
	 The OEM can identify bid or an authorized bidder of OEM can 					
	participate in the tender.					